## BAMOPHOX 450 E - M

# Dissolved Oxygen monitor and controller





## **INSTRUCTION MANUAL**



22, Rue de la Voie des Bans - Z.I. de la Gare - 95100 ARGENTEUIL Tél : (+33) 01 30 25 83 20 - Web : www.bamo.fr Fax : (+33) 01 34 10 16 05 - E-mail : info@bamo.fr Dissolved oxygen monitoring BAMOPHOX 450

11-10-2007

MES

450-02/1

450 M1 02 E

## Dissolved Oxygen monitor and controller **BAMOPHOX 450 E & M**

(Technical information and Manual for LOGGER /RS422 version are on a specific document)

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450 M1 02 B

#### 1. TECHNICAL FEATURES

Displayed parameters: Measurement values - Configuration Menu - Temperature value

Display: Back lighted - 2 lines of 16 alphanumerical characters; 9.2 mm high

Indication: LED alarms status

Configuration: 8 push buttons keyboard on the front - Keyword protected

Scales: 0 to 100% – or mg/L

Accuracy/measurement:  $\pm 0.3\%$ Accuracy/temperature:  $\pm 0.3^{\circ}$ C

Probe input: Screw connectors, IP40

T° compensation: Automatic with an input for a 3 wires Pt 100 Ohm/0°C, range 0...100°C

Manually from 0 to 100°C

Relay outputs: 4 closing contacts (Silver alloy), voltage free

Thresholds: 3 programmable independent thresholds - with adjustable hysteresis 0...100%

and adjustable timer from 0 to 9999 sec

Output relay (S4) Common alarm signal for:

Too long injection – temperature...over scale measurement or open loop

Pt 100 Ohm dysfunctionor probe cleaning function

Contact: Initial resistance 100 milliOhm as a maximum (voltage drop 6 V DC 1 A)

Rated at 831 V AC / 3 A / 277 V AC ; 90 W / 3 A / 30 V DC

Switching capacity (minimum) 100 mA, 5 V DC

(depending of switching frequency, ambient conditions, accuracy)

Mechanical lifetime (minimum) 5 x10<sup>6</sup> operations (180 commutation/min)

Electrical life time (minimum) 2 x10<sup>5</sup> (20 comm./min) [3 A, 125 V AC], [3 A, 30 V DC]

and 10<sup>5</sup> (evaluated charge) for 3 A, 125 V AC

ON/OFF Regulation: Pulse time 0...9999 sec - High and low proportional bandwidth, high and low dead zones

PID Regulation: Proportionality 0...200%, - Integrant and Derivative: 0...999 second

Calibration sequence: Regulation on standby, relay outputs inhibited, analogical outputs stand on last values

Self-cleaning program: Frequency and duration settings, with regulation inhibited and analogical outputs standing on last values

Measurement output: 0/4-20 mA (maxi 600 \_) proportional to measurement, galvanic insulated

T° output / PID: 0/4-20 mA (max 600 \_), scaling 0...100°C, galvanic insulated

Program testing: Simulation through the menu on measurement, temperature, PID and relay outputs

Main power supply: 230 V AC / 50-60 Hz [other on request] - Consumption 10 VA

Models: Panel mounting, IP65, 72 x 144 mm, connections on screw terminal IP40

DIN Rail mounting, connections on screw terminal IP40, only for blind monitor

Wall mounting, IP65, cable glands, connections on screw terminal

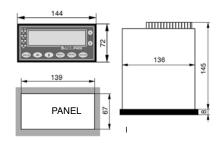
#### OPTION (RS 422 + Logger)

Communication: RS422 output, J-BUS link, binary slave mode, 2400 to 9600 bauds
Data Logger: Cycle average measurement record, with a programmable period,

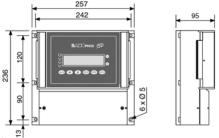
150000 records on MMC (multi media card) / External driver necessary for reading

#### 2. DIMENSIONS

Extension terminal: identical to the panel or wall mounting BAMOPHOX



Panel mounting instrument

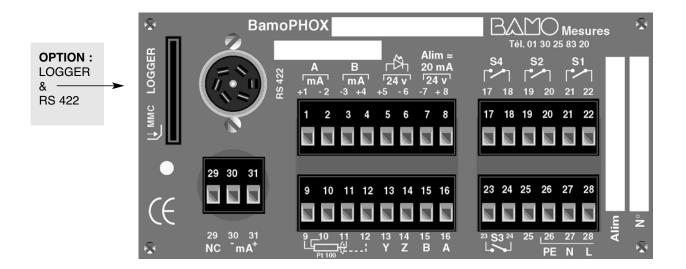


Wall mounting instrument

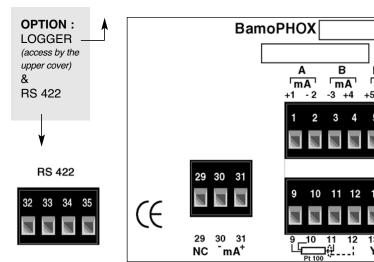
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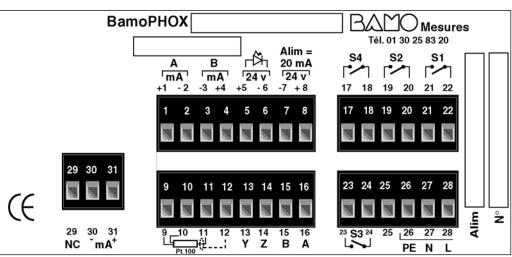
#### 3. WIRING

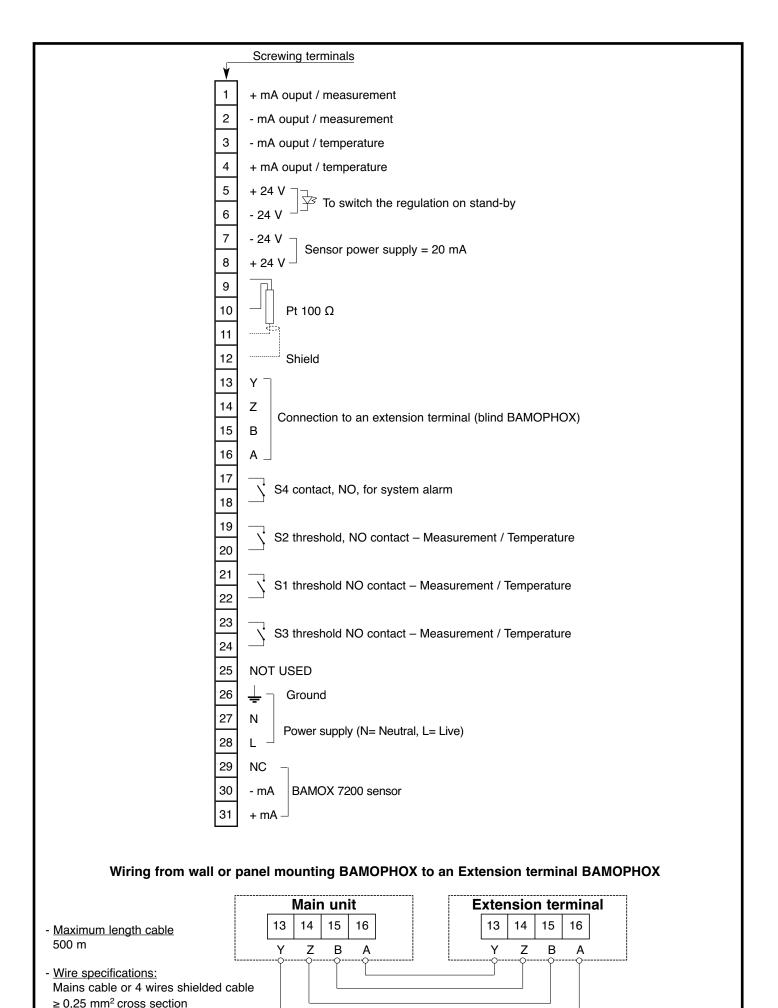
#### WALL MOUNTING MODEL

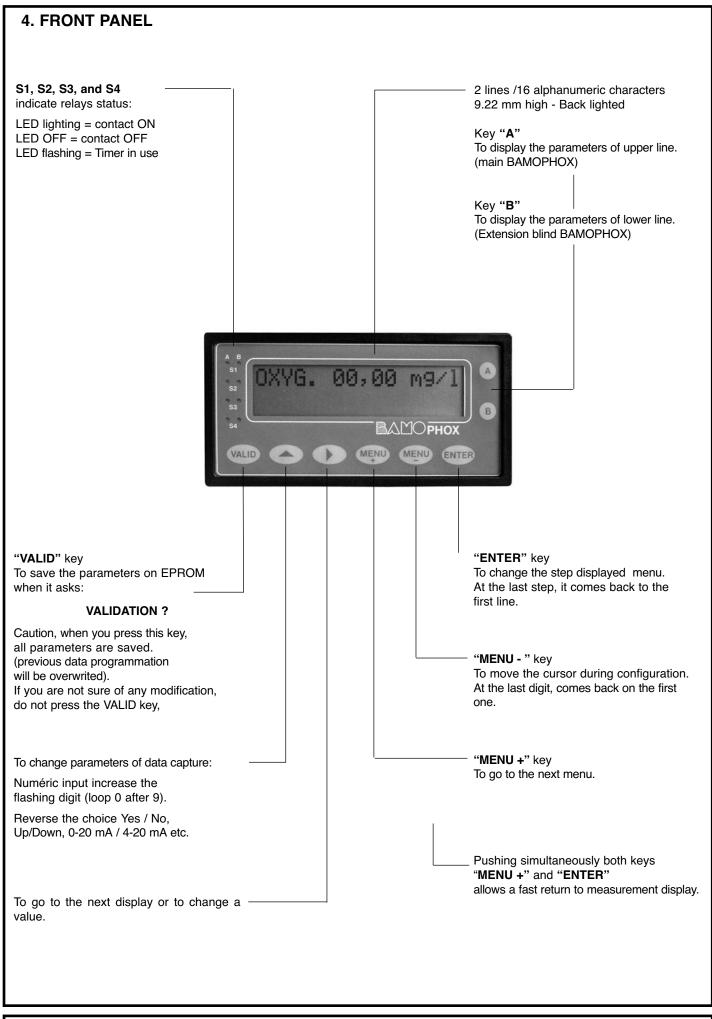


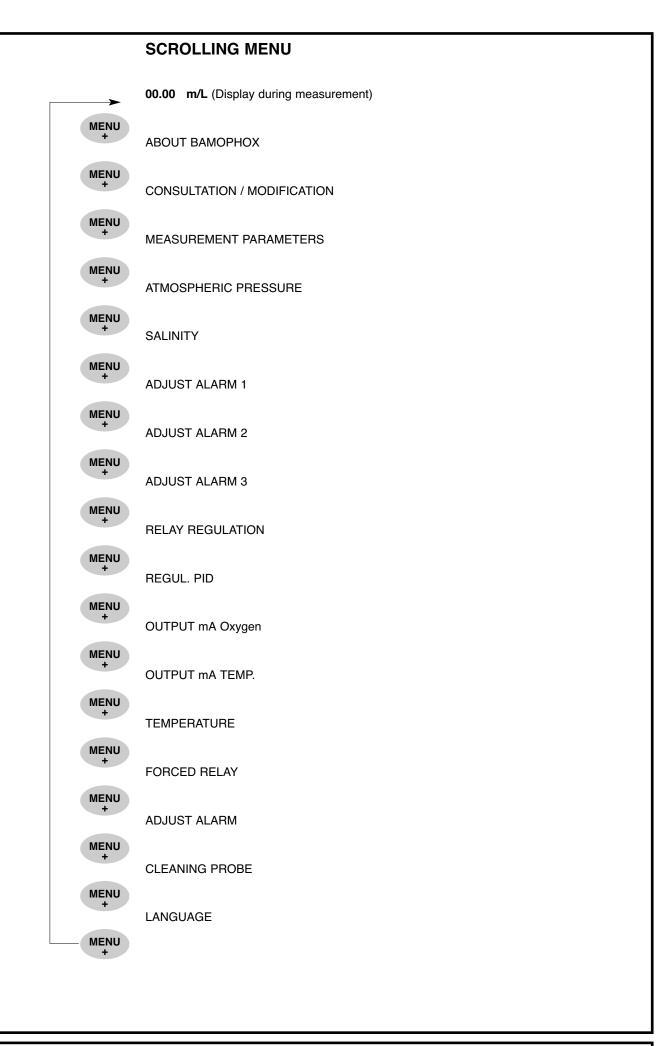
#### PANEL MOUNTING MODEL

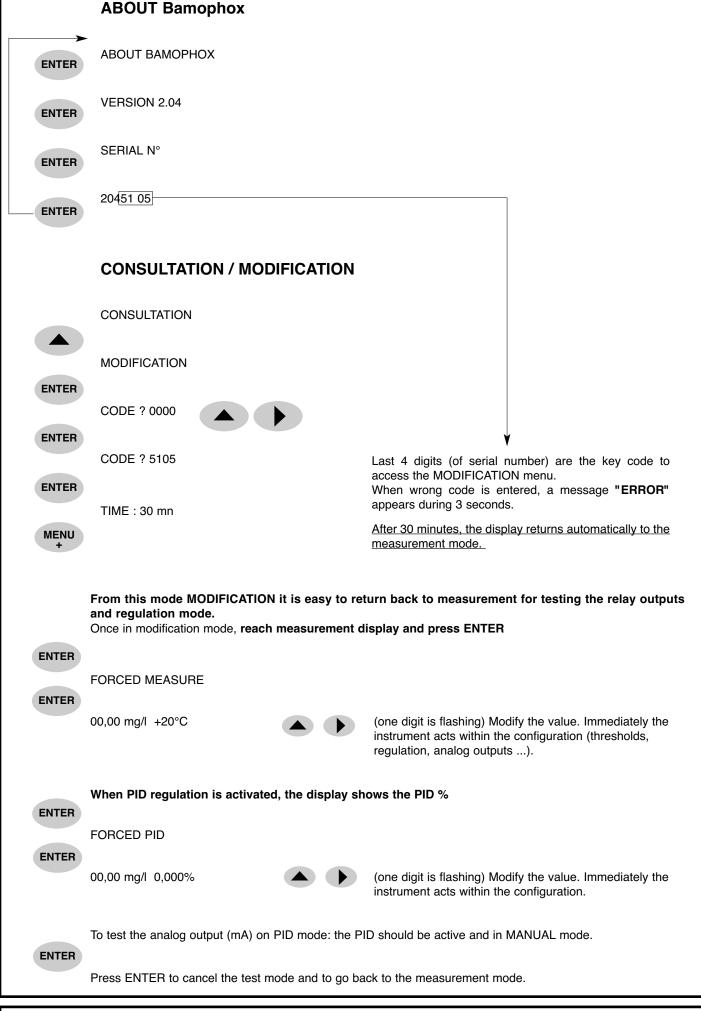


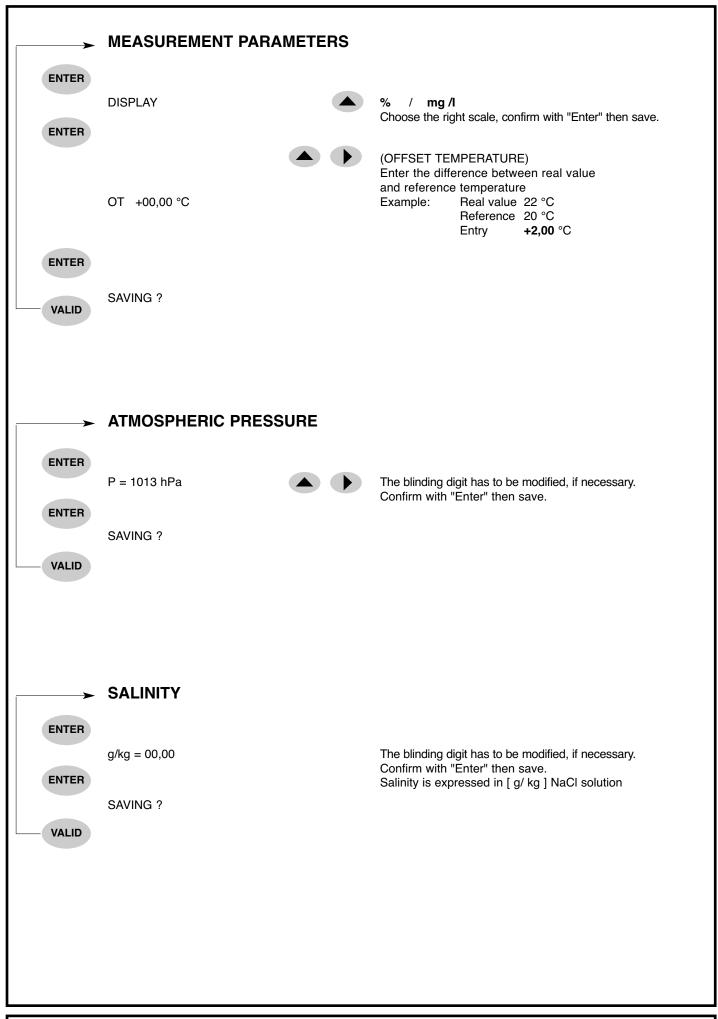


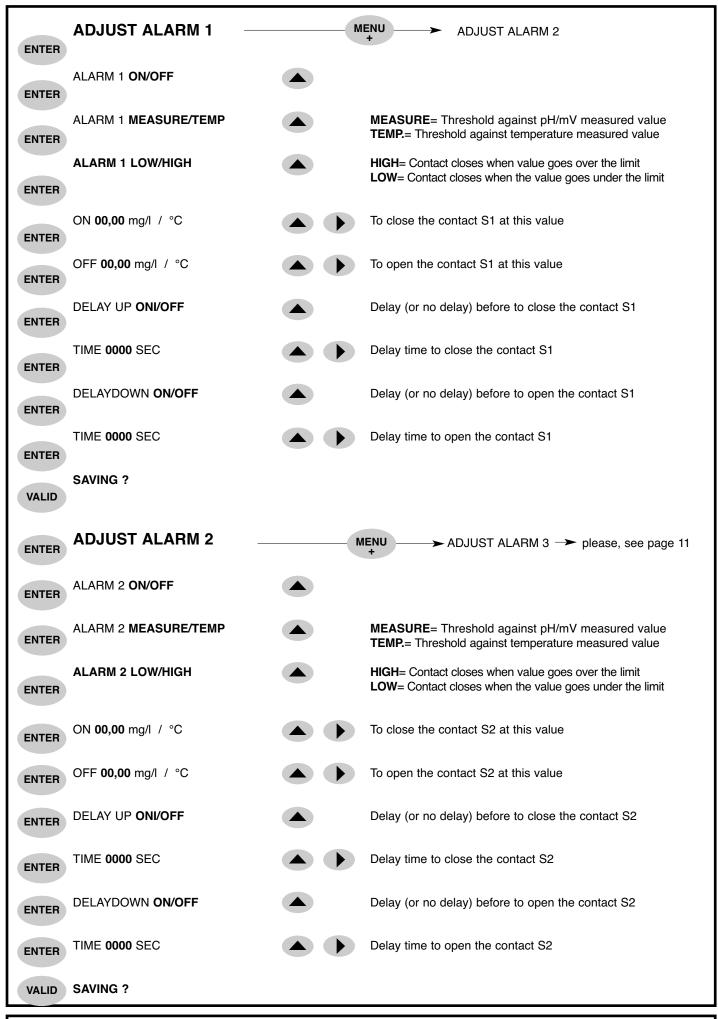


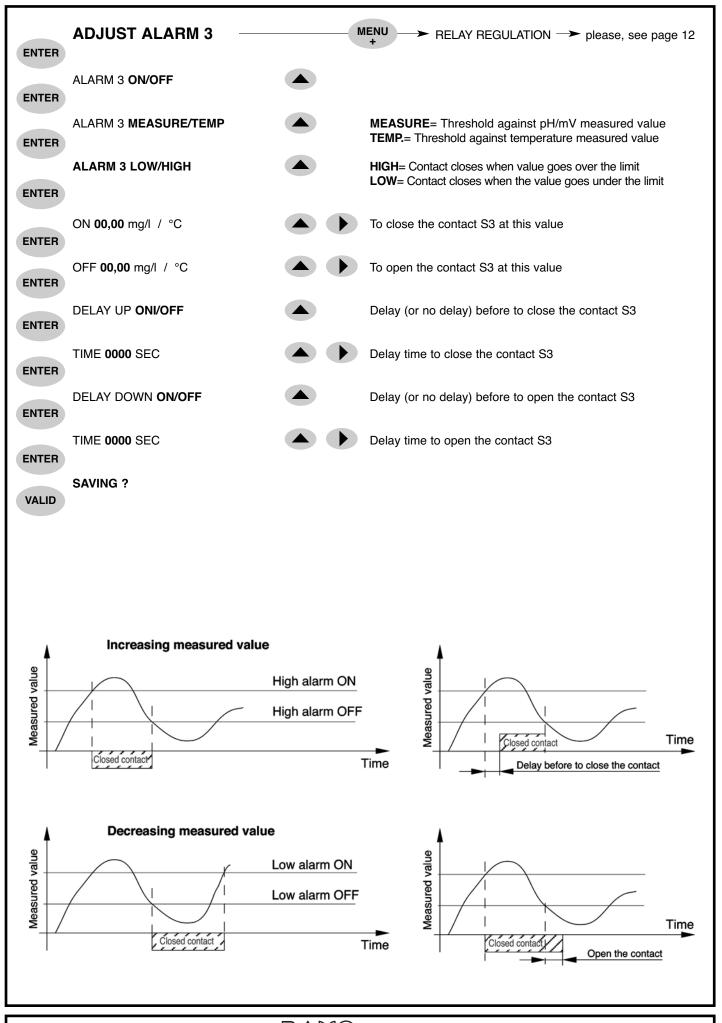


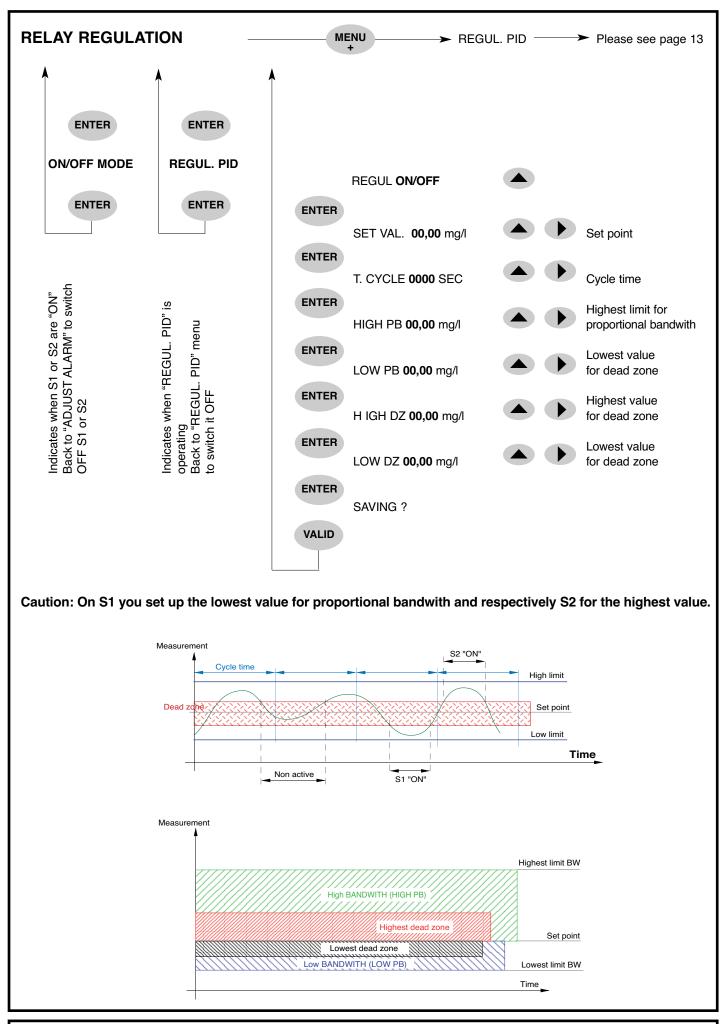


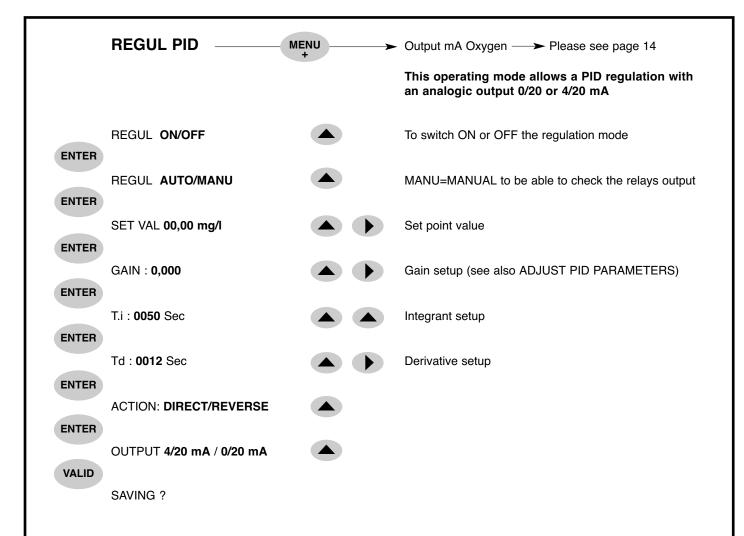












To switch the PID regulation on stand-by, please input 24 V= 20 mA on terminals 5(+) and 6(-).

#### **ADJUST PID PARAMETERS**

In order to determinate the setup values for PID regulation, we recommend to use the Ziegler-Nichols open loop method

#### Proceed as following:

- Connect a recorder to the analogic measurement output or write the reading measurement values for then to draw the graph  $f_{(\text{time})}$
- Switch on the PID regulation in MANUAL mode
- Reach to and keep close the measurement value to the set point, adjusting the PID output
- Apply on ΔCde a step of 10 % (for instance) on the analogic output (Cde).

**Example:** if the value is 30,00 %, apply 40,00 %

- Note on the graph the corresponding timing.
- Determinate on this graph both  $\boldsymbol{t}$  ant  $\boldsymbol{T}\!:$

t = delay of response

T = Time corresponding to the same variation in % of measurement ( $\Delta m$ ) and the analogic output ( $\Delta Cde$ ),  $\Delta m = \Delta Cde$ . This value may be found out on the slope.

- Modify the PID parameters as following:

Regulation	Gain	Ti(s)	Td(s)
PID	1,2 x T/t	2 x t	0,5 x t
PI	0,9 x T/t	3,3 x t	0
Р	T/t	9999	0

